



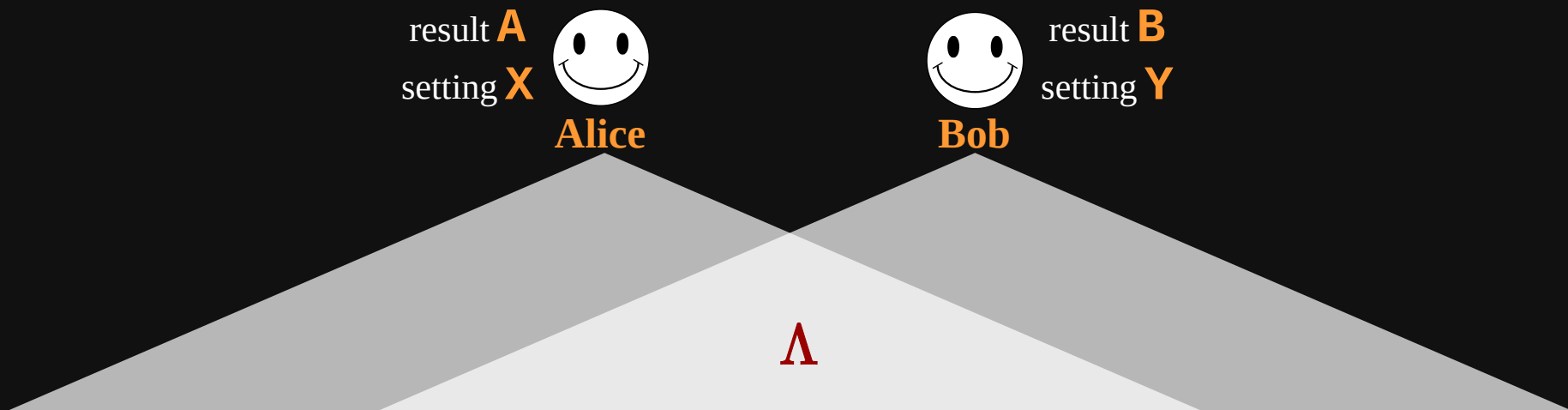
Graphical Tests of Causality

joint work with Eleftherios-Ermis Tselentis

Ämin Baumeler, Università della Svizzera italiana

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PRA 111, 052211 (2025) *and ongoing...*



$$p(a, b|x, y) = \sum_{\lambda} p(\lambda) \, p(a|x, \lambda) \, p(b|y, \lambda)$$

$$\Pr[A \oplus B = X \cdot Y] \leq 3/4$$

$$p(a, b|x, y) = \sum_{\lambda} p(\lambda) \ p(a|x, \lambda) \ p(b|y, \lambda)$$

$$p(00|00) \quad p(01|00) \quad p(10|00) \quad p(11|00)$$

$$p(00|01) \quad p(01|01) \quad p(10|01) \quad p(11|01)$$

$$p(00|10) \quad p(01|10) \quad p(10|10) \quad p(11|10)$$

$$p(00|11) \quad p(01|11) \quad p(10|11) \quad p(11|11)$$

$$p(a, b|x, y) = \sum_{\lambda} p(\lambda) \ p(a|x, \lambda) \ p(b|y, \lambda)$$

$$p(00|00) \quad p(01|00) \quad p(10|00)$$

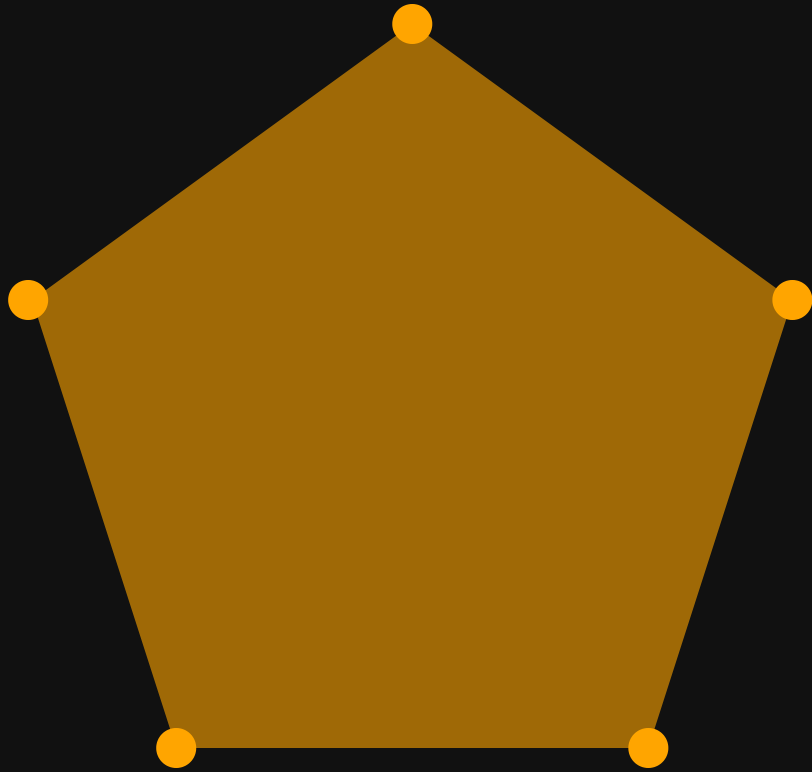
$$p(00|01) \quad p(01|01) \quad p(10|01)$$

$$p(00|10) \quad p(01|10) \quad p(10|10)$$

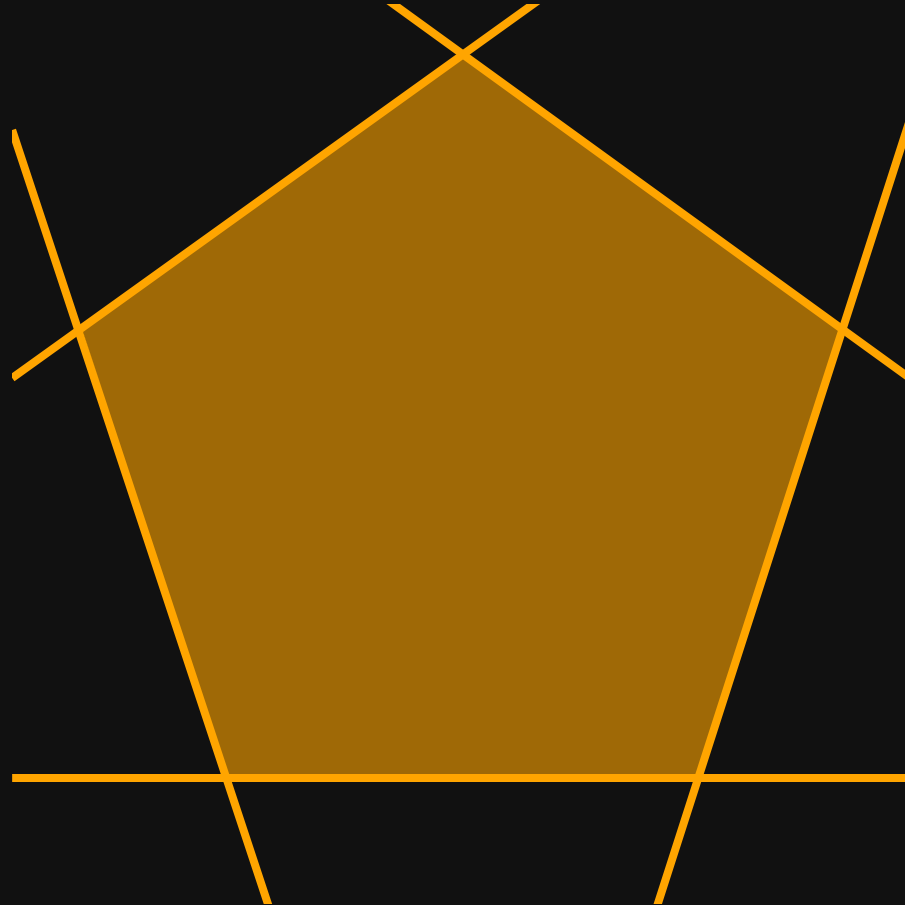
$$p(00|11) \quad p(01|11) \quad p(10|11)$$

Geometric representation: **convex polytope**

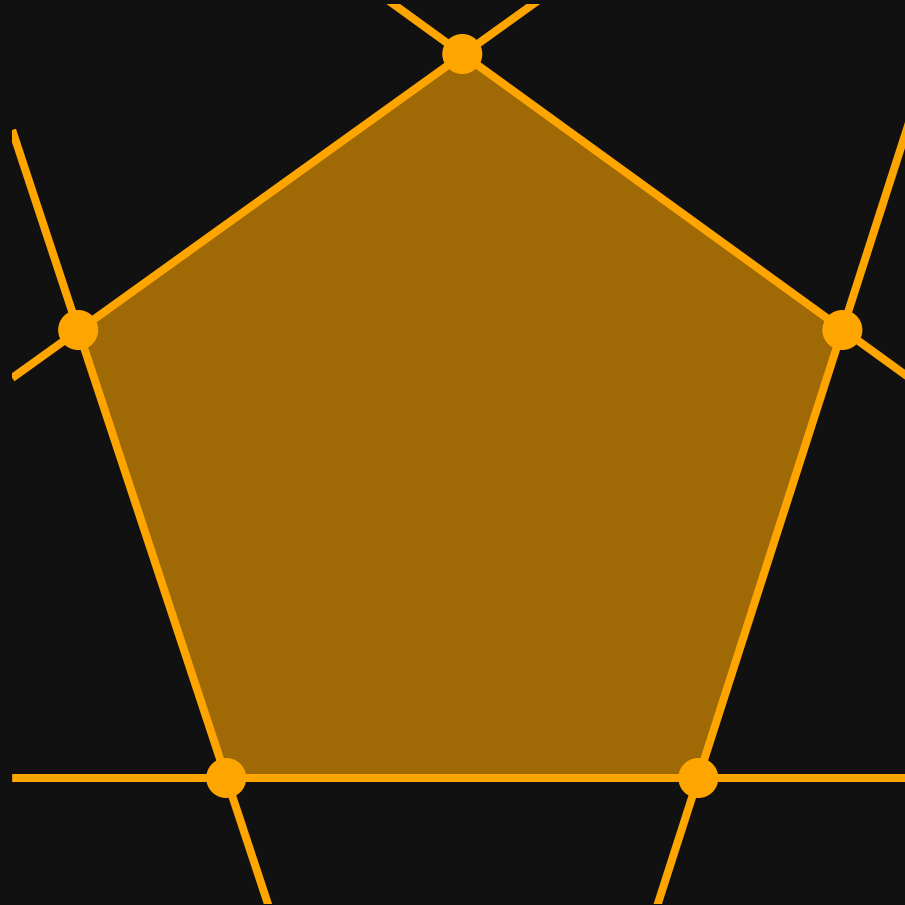




vertex representation

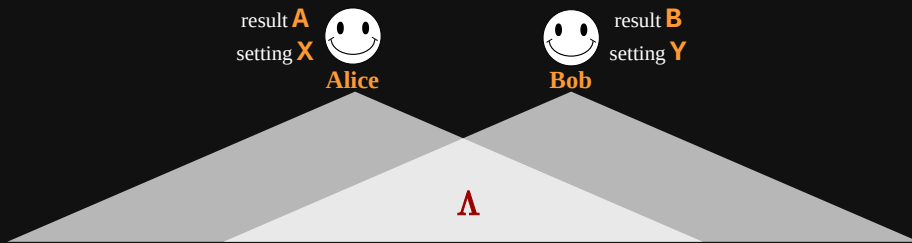


halfspace representation



Bell inequality defines **facet**

Outline



0. Bell Test of Locality

1. Single-Output Scenario

2. SOS Polytopes

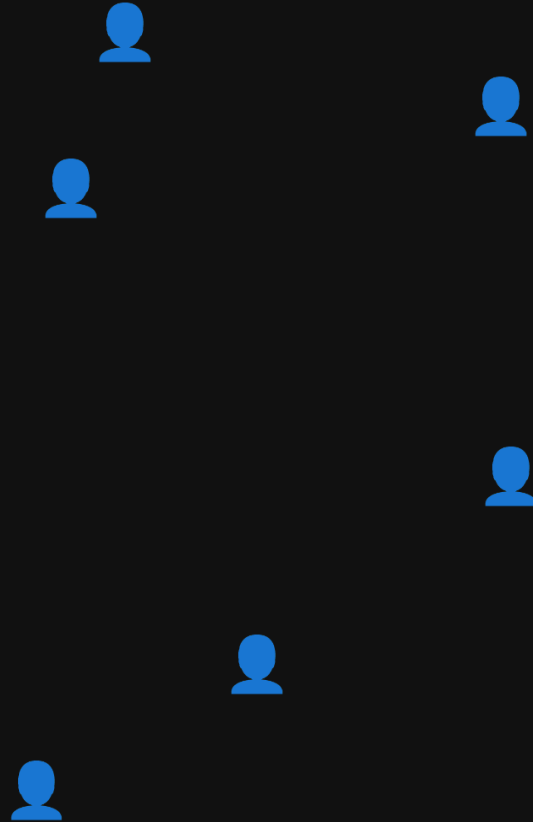
3. Graphical Games

4. Notions of Causality

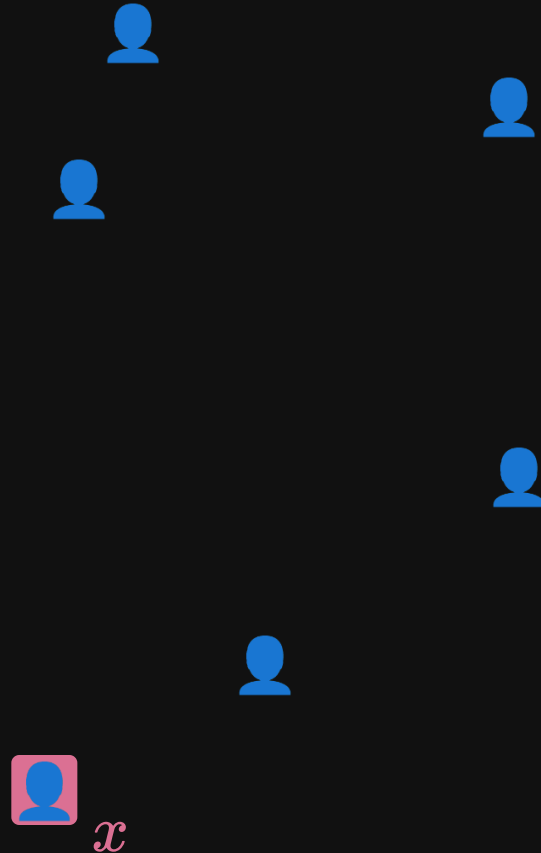
5. End

The Single-Output Scenario

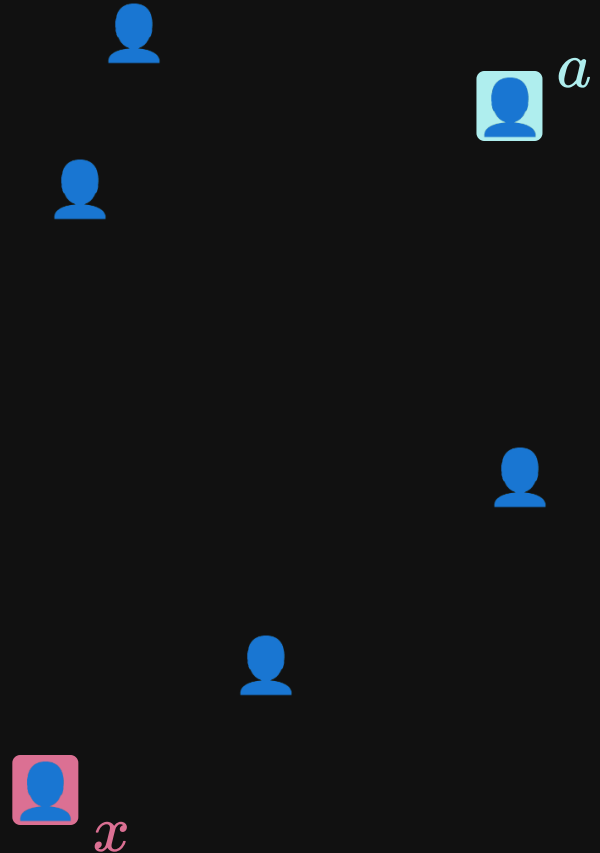
- n parties $\{0, 1, \dots, n - 1\}$



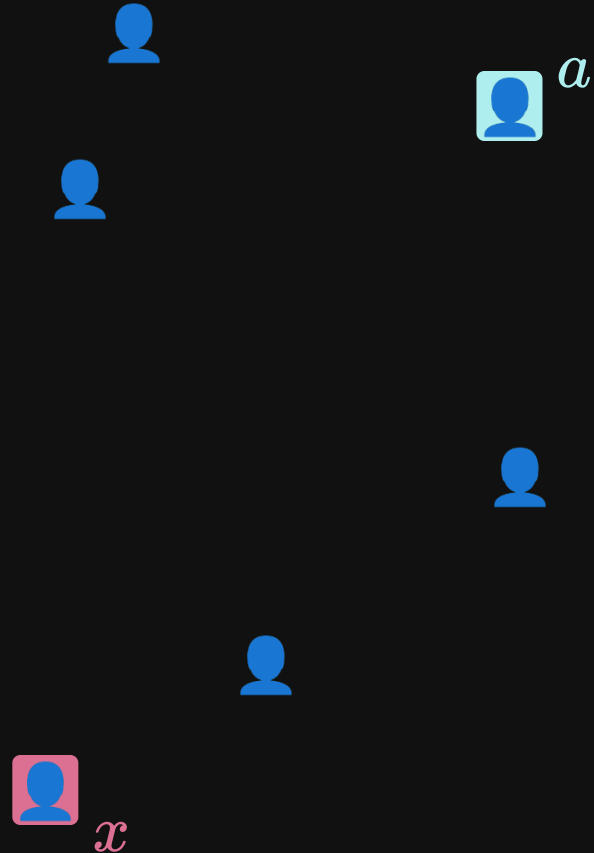
- n parties $\{0, 1, \dots, n - 1\}$
- party s with input x



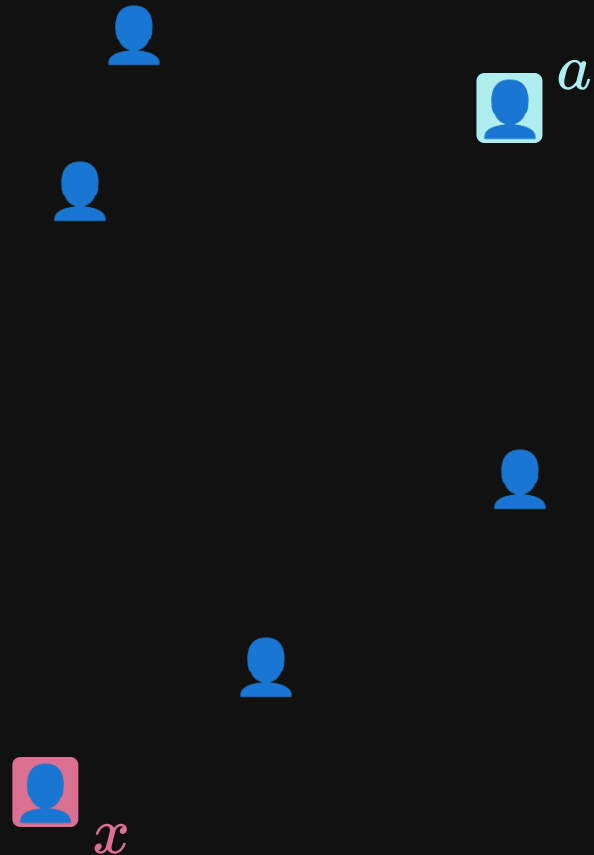
- n parties $\{0, 1, \dots, n - 1\}$
- party s with input x
- party r with output a



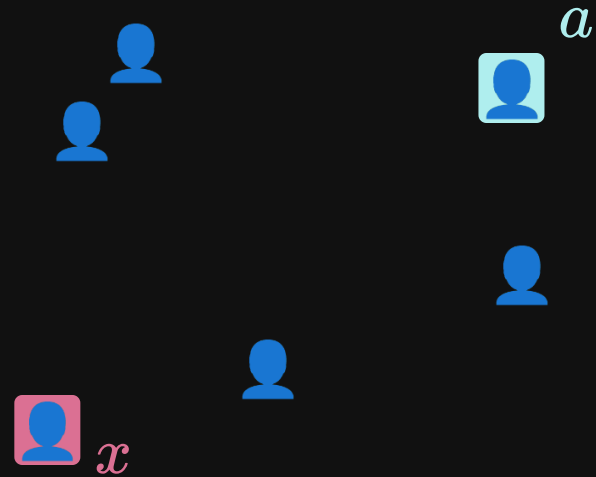
- n parties $\{0, 1, \dots, n - 1\}$
- party s with input x
- party r with output a
- $s \neq r$, x and a binary



- n parties $\{0, 1, \dots, n - 1\}$
- party s with input x
- party r with output a
- $s \neq r$, x and a binary
- all parties learn s and r



- n parties $\{0, 1, \dots, n - 1\}$
- party s with input x
- party r with output a
- $s \neq r$, x and a binary
- all parties learn s and r



$$p(a|s, r, x)$$

$$p(a|s,r,x)$$

$a \setminus s,r,x$	010	011	020	021	...	100	101	120	121	...
0	p_{010}^0	p_{011}^0	p_{020}^0	p_{021}^0		p_{100}^0	p_{101}^0	p_{120}^0	p_{121}^0	
1	p_{010}^1	p_{011}^1	p_{020}^1	p_{021}^1		p_{100}^1	p_{101}^1	p_{120}^1	p_{121}^1	

$$p(a|s,r,x)$$

$a \setminus s,r,x$	010	011	020	021	...	100	101	120	121	...
0	p_{010}^0	p_{011}^0	p_{020}^0	p_{021}^0		p_{100}^0	p_{101}^0	p_{120}^0	p_{121}^0	

$$p(a = 0 | s, r, x)$$

$x \setminus s, r$	01	02	...	10	12	...
0	p_{010}^0	p_{020}^0		p_{100}^0	p_{120}^0	
1	p_{011}^0	p_{021}^0		p_{101}^0	p_{121}^0	

$$p(a = 0 | s, r, x)$$

$x \setminus s, r$	01	02	...	10	12	...
0	p_{010}^0	p_{020}^0		p_{100}^0	p_{120}^0	
1	p_{011}^0	p_{021}^0		p_{101}^0	p_{121}^0	

$$d = 2n(n - 1)$$

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$x \setminus s, r$	01	02	...	10	12	...
0	p_{010}^0	p_{020}^0		p_{100}^0	p_{120}^0	
1	p_{011}^0	p_{021}^0		p_{101}^0	p_{121}^0	

Polytope $\mathcal{P}$: General Properties

$x \setminus s, r$	01	02	...	10	12	...
0	0	1		1	0	
1	0	0		1	0	

Polytope $\mathcal{P}$: General Properties

Suppose $ext(\mathcal{P}) \subseteq \{0, 1\}^d$

$x \setminus s, r$	01	02	...	10	12	...
0	0	1		1	0	
1	0	0		1	0	

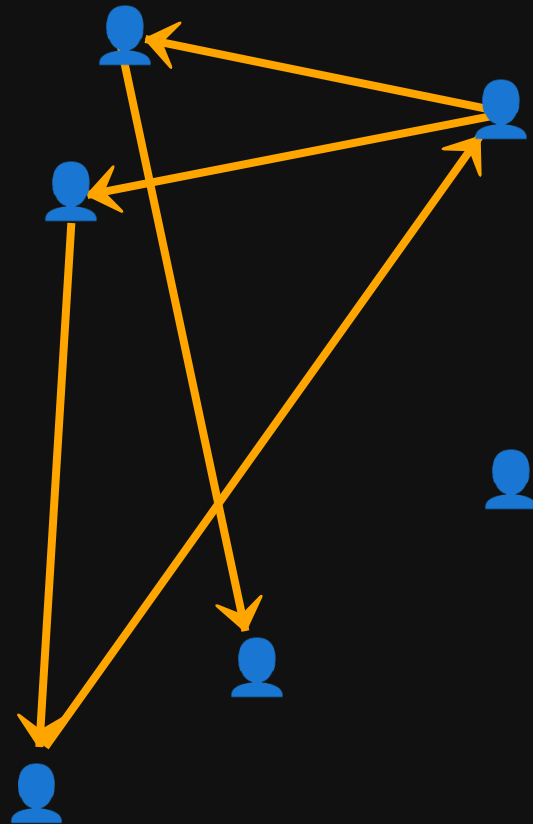
$x \setminus s, r$	01	02	...	10	12	...
0	0	1		1	0	
1	0	0		1	0	

$x \setminus s, r$	01	02	...	10	12	...
0	0	$1 \oplus 1$		1	0	
1	0	$0 \oplus 1$		1	0	

Equivalence relation

$x \setminus s, r$	01	02	...	10	12	...
0	0	1		1	0	
1	0	0		1	0	
$\oplus$	0	1		0	0	

$$\{q \mid q \sim p, p, q \in \text{ext}(\mathcal{P})\} :$$



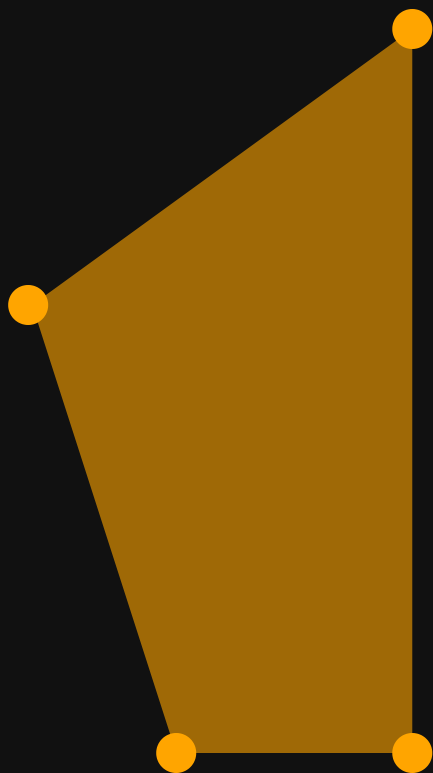
Projection of $\mathcal{P}$ to the polytope $\mathcal{Q}$ of directed graphs



Projection of $\mathcal{P}$ to the polytope $\mathcal{Q}$ of directed graphs



Projection of $\mathcal{P}$ to the polytope $\mathcal{Q}$ of directed graphs



Lifting Lemma

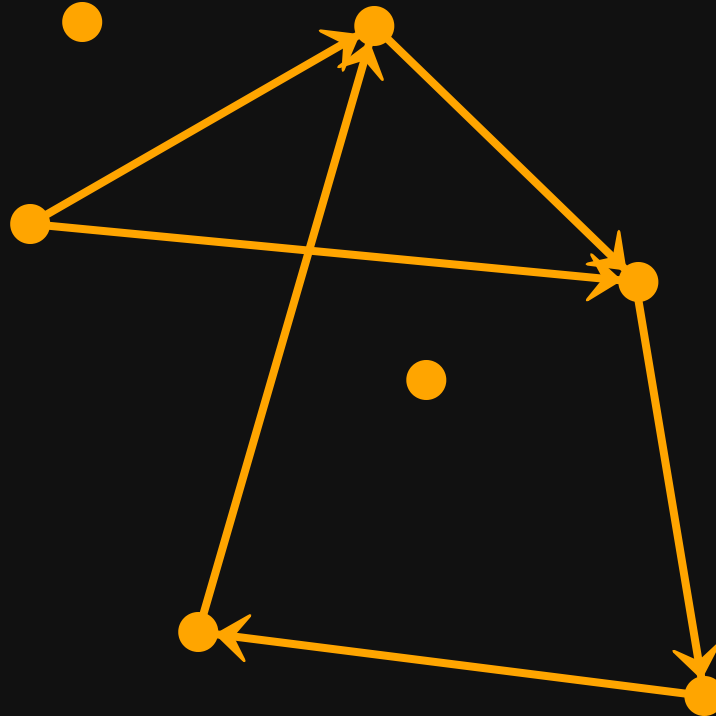
If $\mathcal{P}$ is full-dimensional and deterministic, then every nontrivial and nonnegative facet-defining inequality of the graph polytope $\mathcal{Q}$ describes a facet-defining inequality of $\mathcal{P}$.

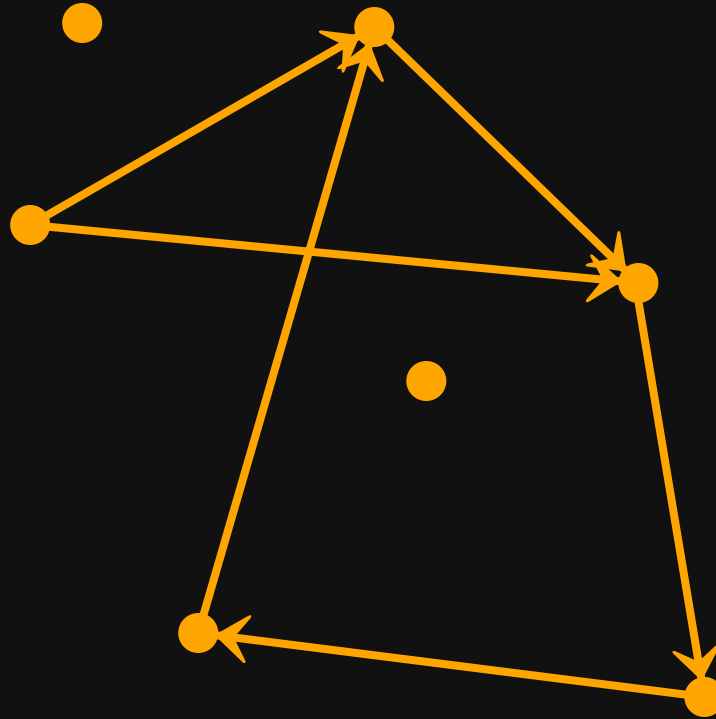
Outline



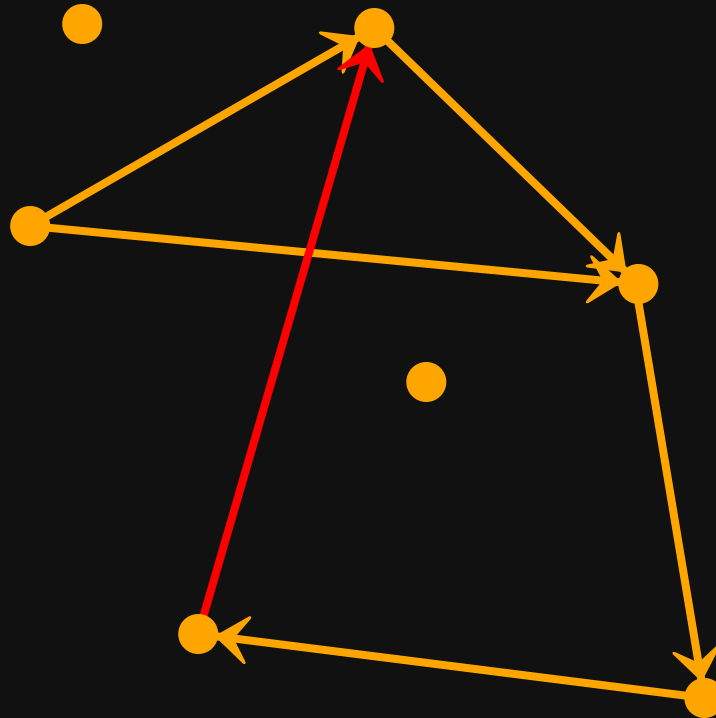
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Graphical Games

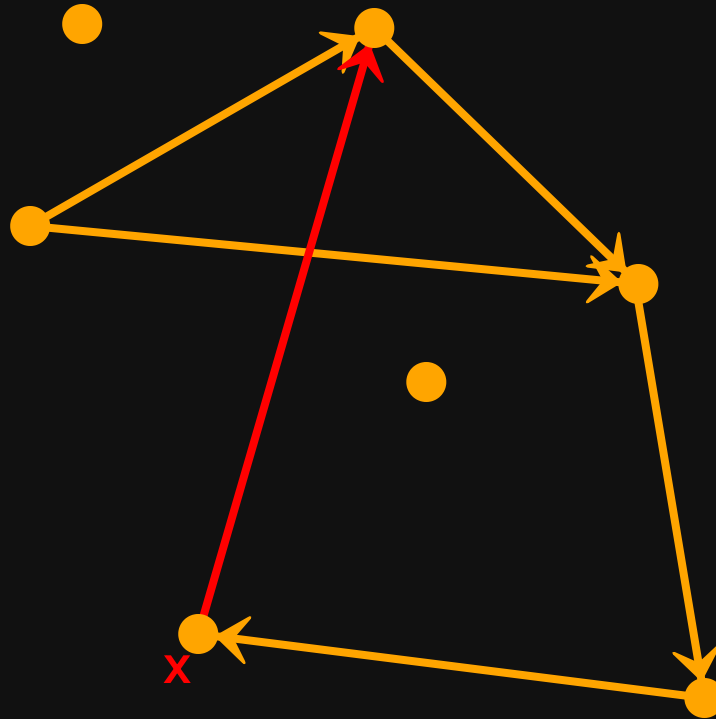




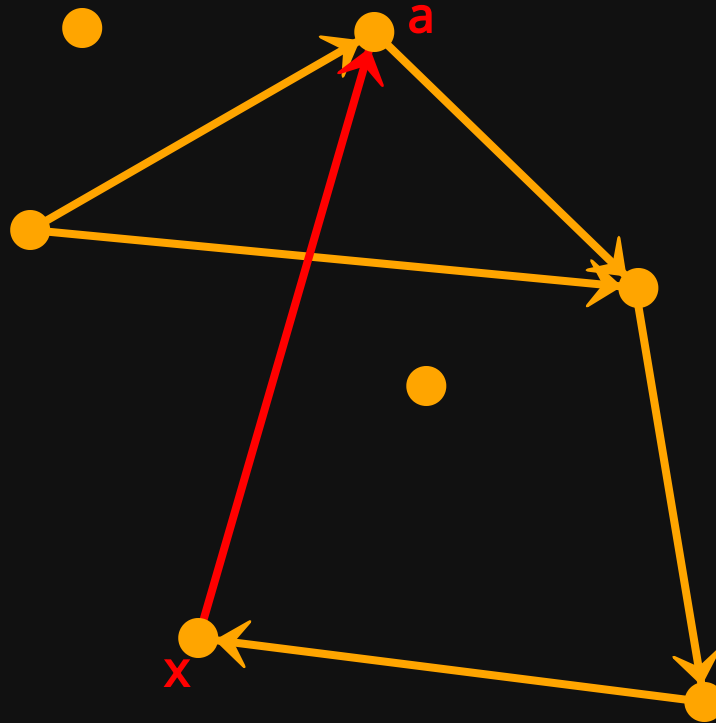
Game $\mathcal{G}(D)$ from directed graph $D = (V(D), E(D))$



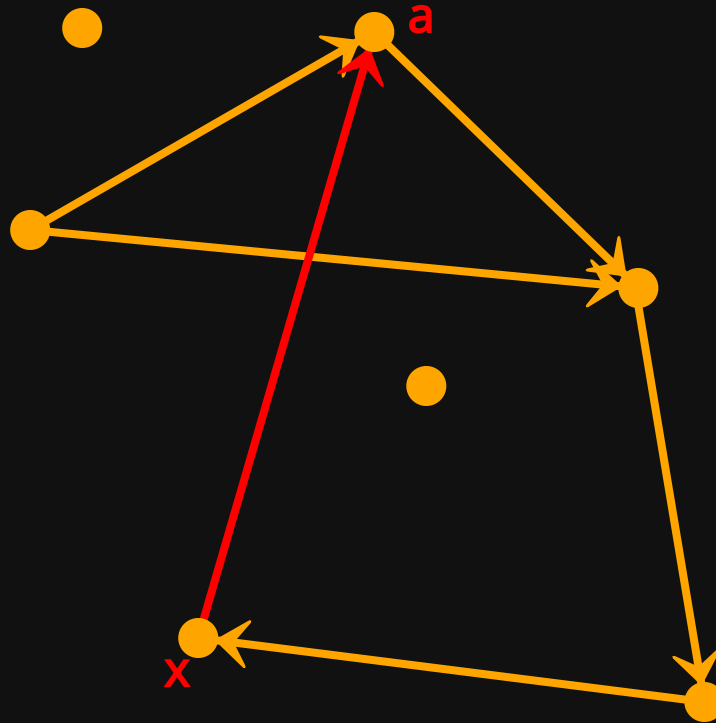
Referee broadcasts $(s \rightarrow r) \in_R E(D)$



... announces $x \in_R \{0, 1\}$ to r

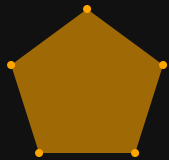


Party r produces a guess $a \in \{0, 1\}$



The parties **win** $\mathcal{G}(D)$ whenever $a = x$.

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Notions of Causality

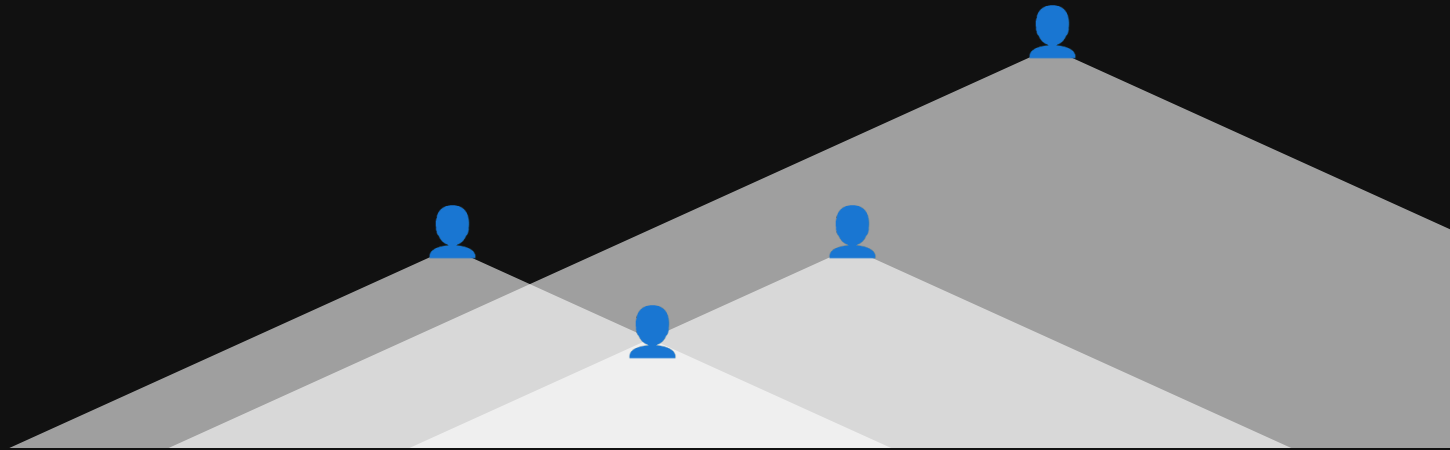
Notions of Causality

- Static causal order
- Dynamic causal order
- Bicausal
- ...

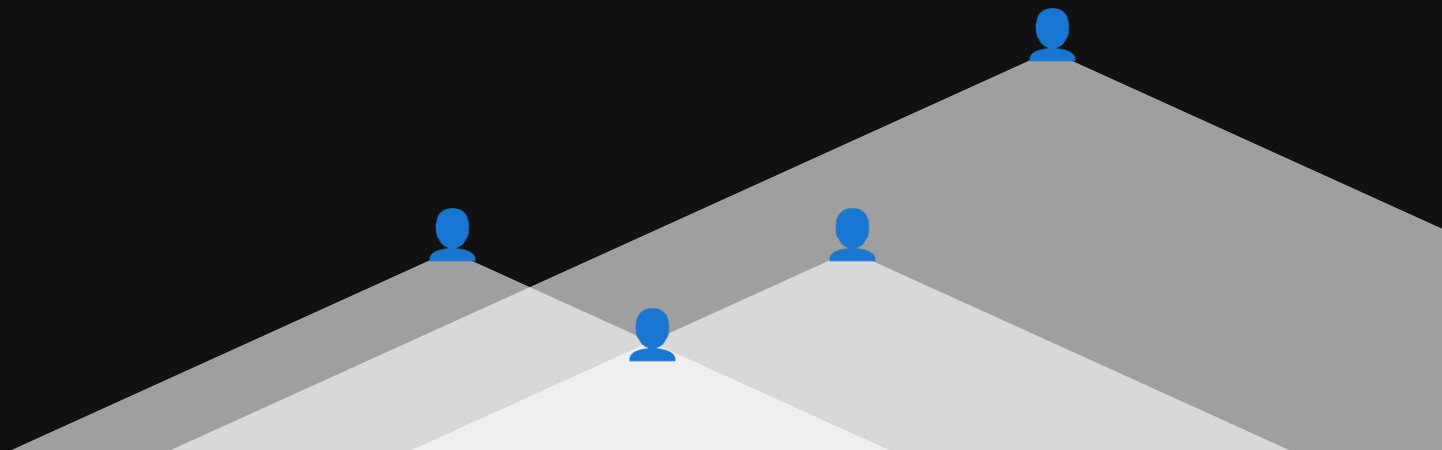
Notions of Causality

- Static causal order (SR)
- Dynamic causal order (GR)
- Bicausal
- ...

Static Causal Order



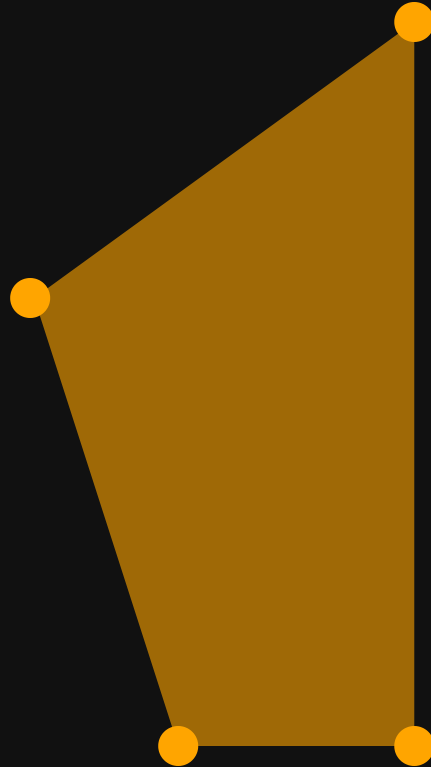
Static Causal Order



$$p(a|s, r, x) =$$

$$\sum_{\sigma: s \not\prec_{\sigma} r} p(\sigma) p_{\sigma}^{\not\prec}(a|s, r) + \sum_{\sigma: s \preceq_{\sigma} r} p(\sigma) p_{\sigma}^{\preceq}(a|s, r, x)$$

Static Causal Order: the DAG polytope

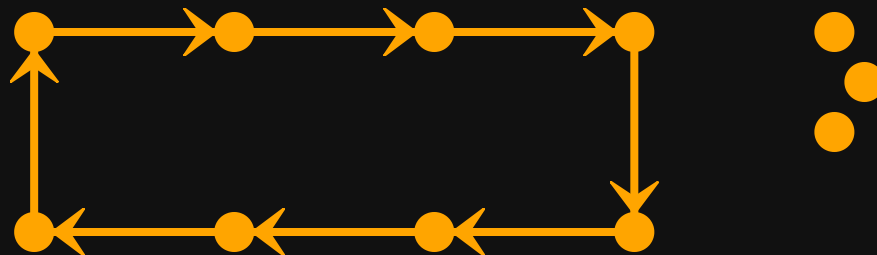


Static Causal Order: **the DAG polytope**



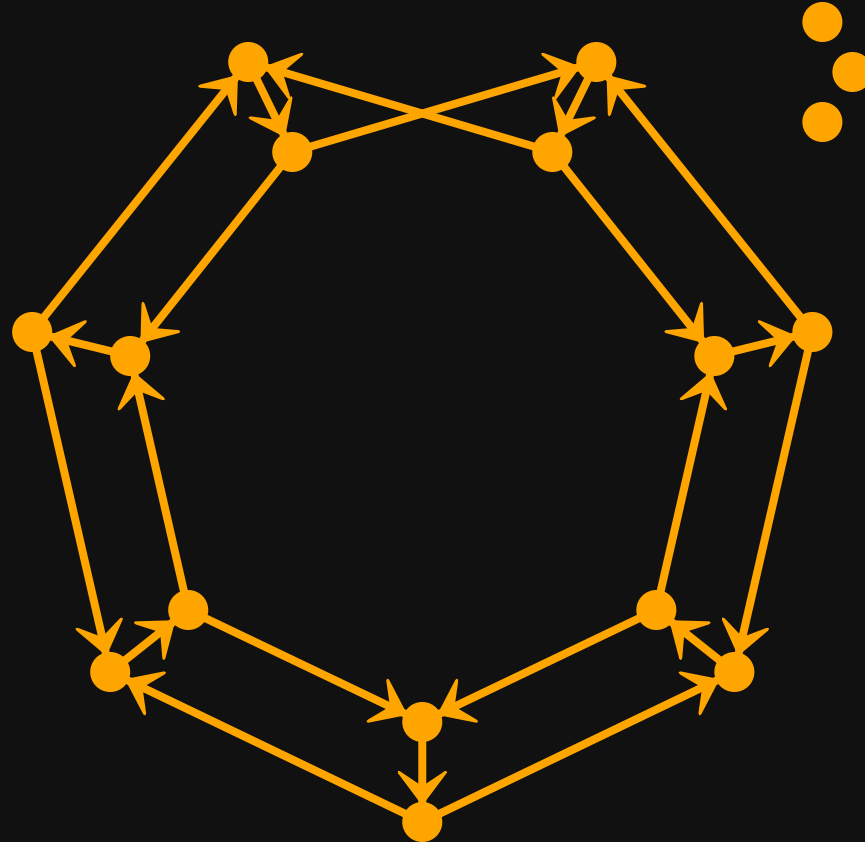
- k -cycle inequalities
- k -fence inequalities
- k -Möbius inequalities
- ...

k -cycle inequalities



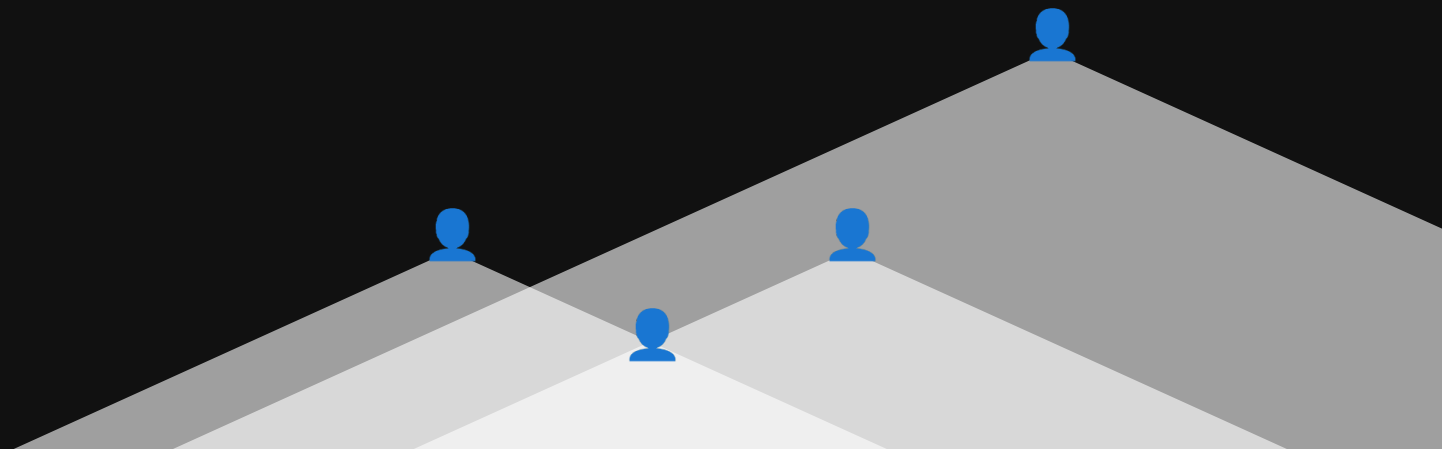
$$\Pr[\text{win } \mathcal{G}(D)] \leq 1 - \frac{1}{2k}$$

k -Möbius inequalities

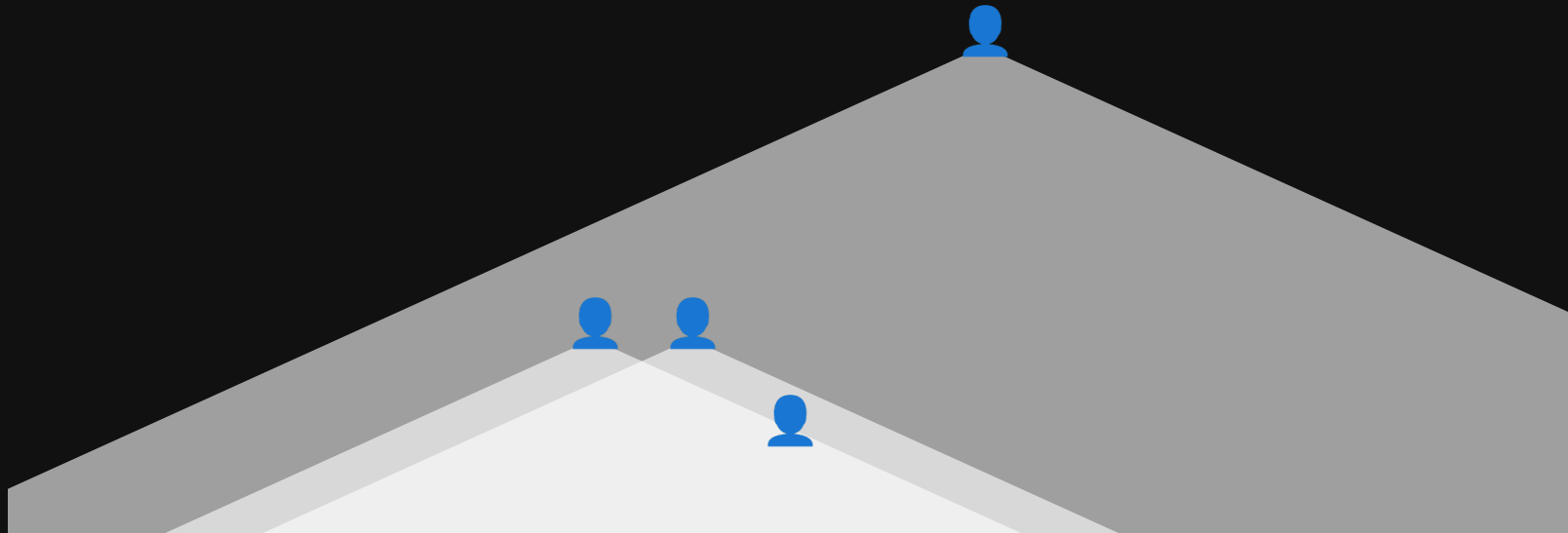


$$\Pr[\text{win } \mathcal{G}(D)] \leq 1 - \frac{k+1}{12k} < \frac{11}{12}$$

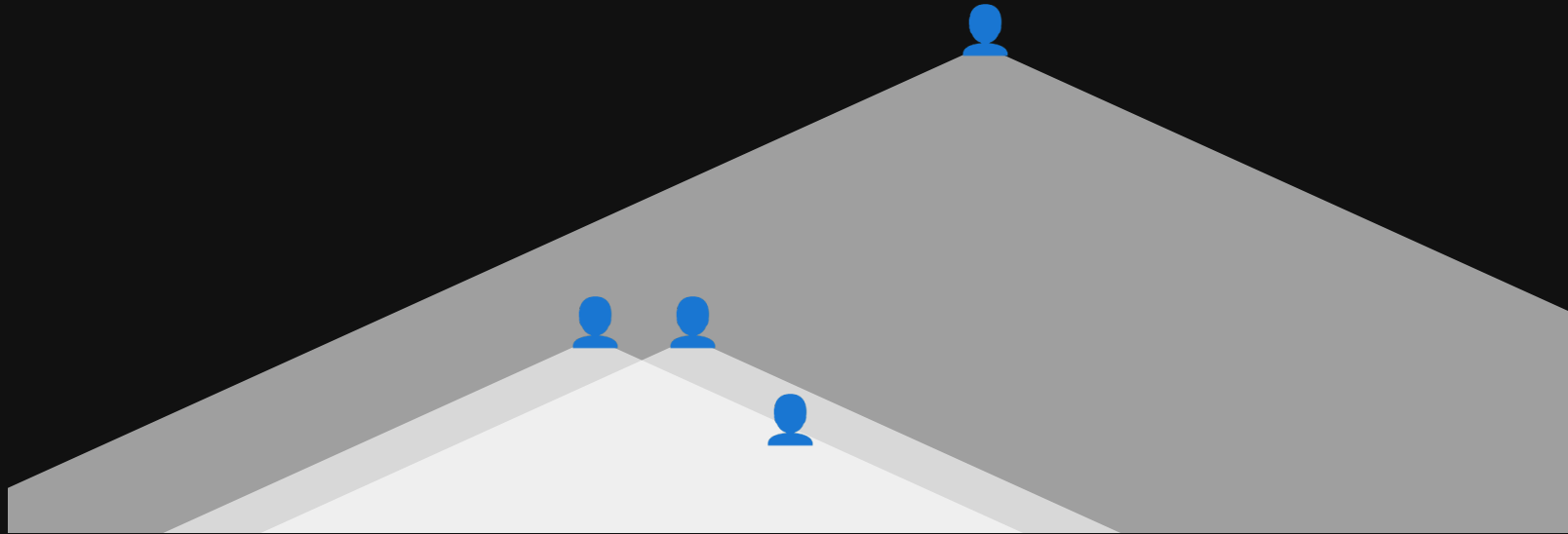
Dynamic Causal Order



Dynamic Causal Order



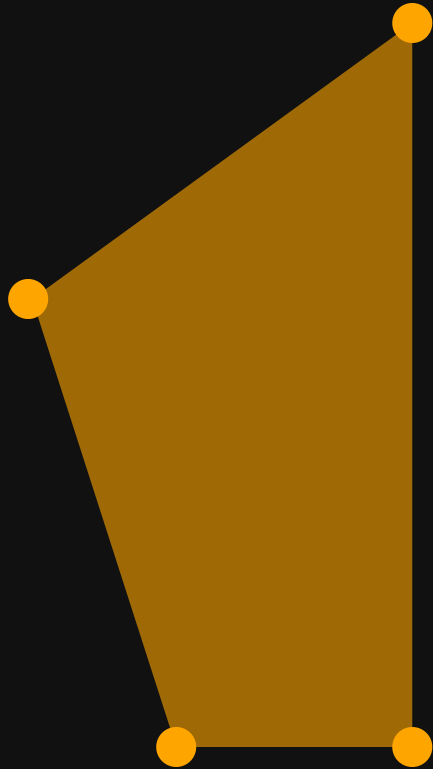
Dynamic Causal Order



$$p(a|s, r, x) =$$

$$p_{\text{first}}(r) p_0(a|s, r) + (1 - p_{\text{first}}(r)) p_1(a|s, r, x)$$

Dynamic Causal Order: **the source graph polytope**

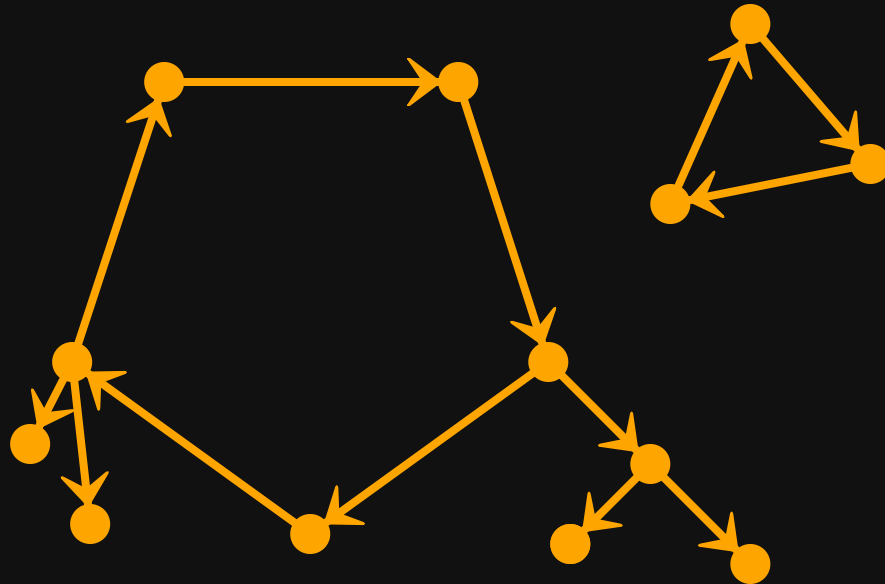


Dynamic Causal Order: **the source graph polytope**



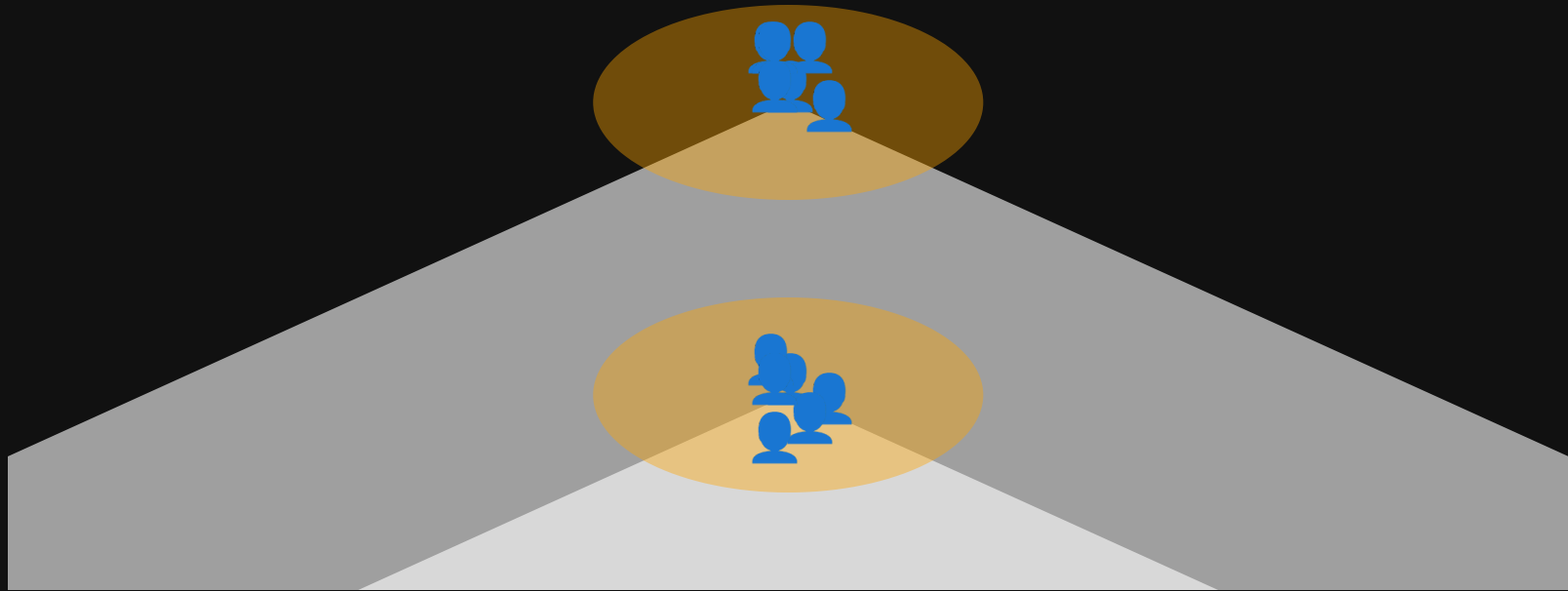
- Kefalopoda inequalities
- (more?)

Kefalopoda inequalities

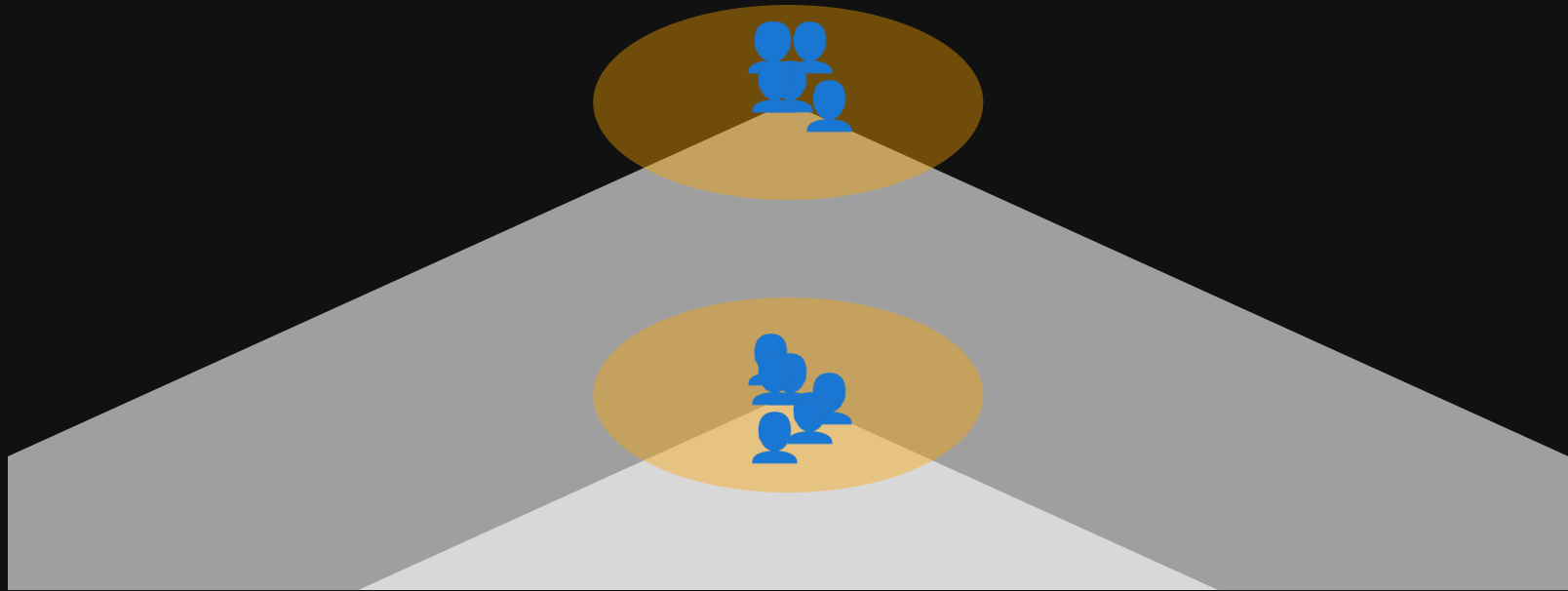


$$\Pr[\text{win } \mathcal{G}(D)] \leq 1 - \frac{1}{n}$$

Bicausal



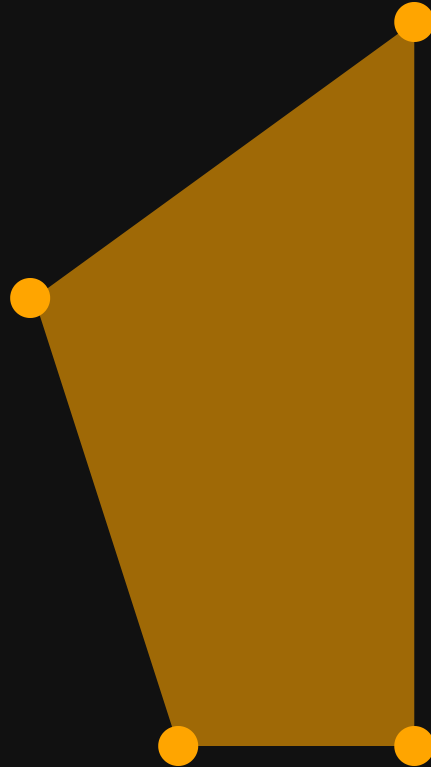
Bicausal



$$p(a|s, r, x) =$$

$$\sum_{\mathcal{F}: s \notin \mathcal{F} \wedge r \in \mathcal{F}} p(\mathcal{F}) p_0(a|s, r) + \sum_{\mathcal{F}: r \in \mathcal{F} \rightarrow s \in \mathcal{F}} p(\mathcal{F}) p_1(a|s, r)$$

Bicausal: **the not-strong polytope**

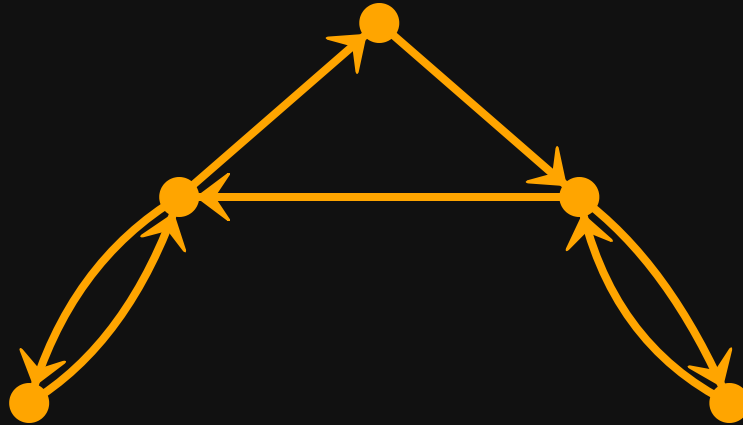


Bicausal: **the not-strong polytope**



- Minimally strong
- (more!)

Minimally strong inequalities



$$\Pr[\text{win } \mathcal{G}(D)] \leq 1 - \frac{1}{|E(D)|}$$

Thank You